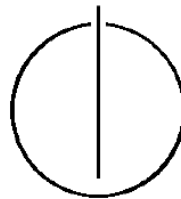


FAKULTÄT FÜR INFORMATIK

DER TECHNISCHEN UNIVERSITÄT MÜNCHEN

Probabilistic Cellular Automata

Carlos Camino



Outline of the Presentation

1. CELLULAR AUTOMATA
2. MAJORITY PROBLEM
3. TOOL
4. ANALYSIS
5. RESULTS
6. CONCLUSIONS

1. Cellular Automata

1. Cellular Automata

Cells (**n = 10**)

0	1	2	3	4	5	6	7	8	9
---	---	---	---	---	---	---	---	---	---

1. Cellular Automata

0	1	2	3	4	5	6	7	8	9
---	---	---	---	---	---	---	---	---	---



Neighborhood ($r = 1$)

1. Cellular Automata



States ($s = 2$)

 = 0

 = 1

1. Cellular Automata

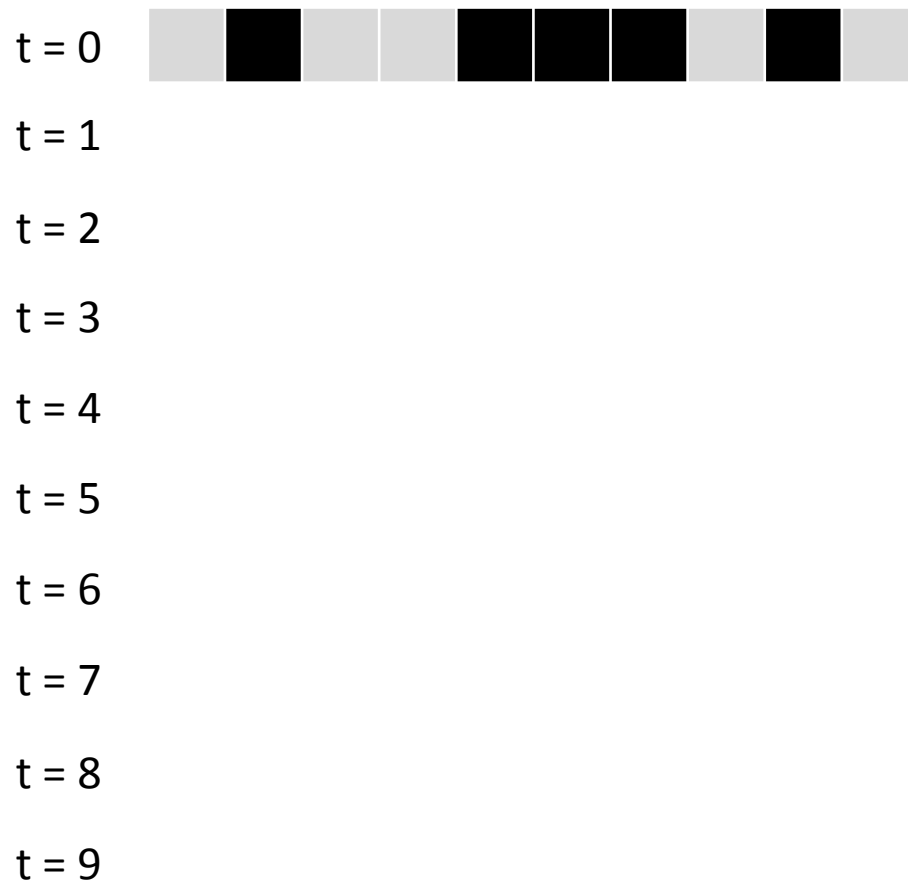


Rule

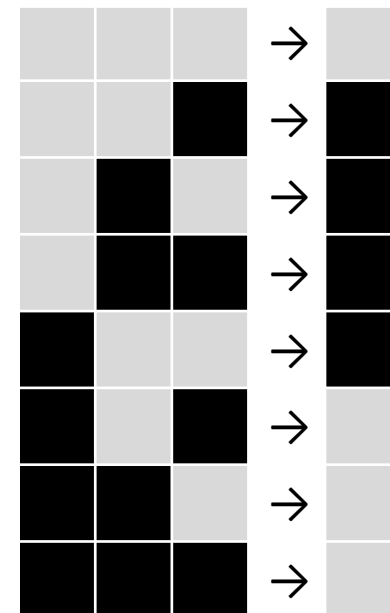
			→	
			→	
			→	
			→	
			→	
			→	
			→	
			→	
			→	
			→	

1. Cellular Automata

Configuration

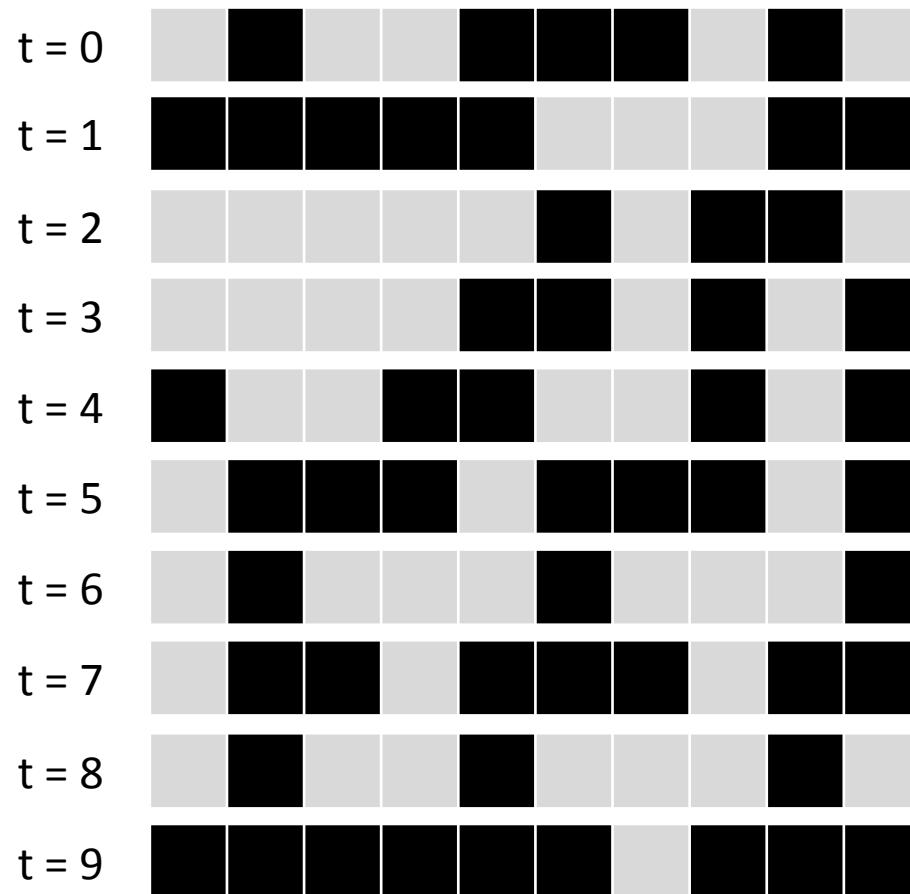


Rule

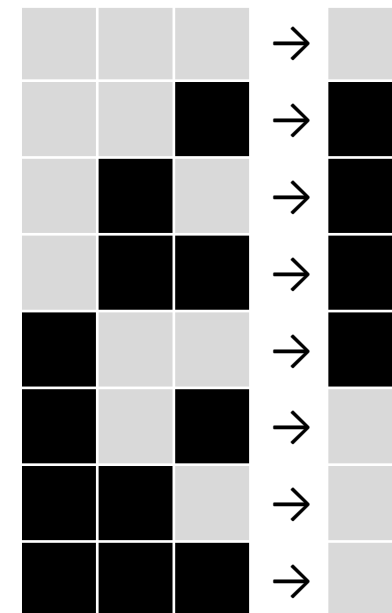


1. Cellular Automata

Configuration



Rule

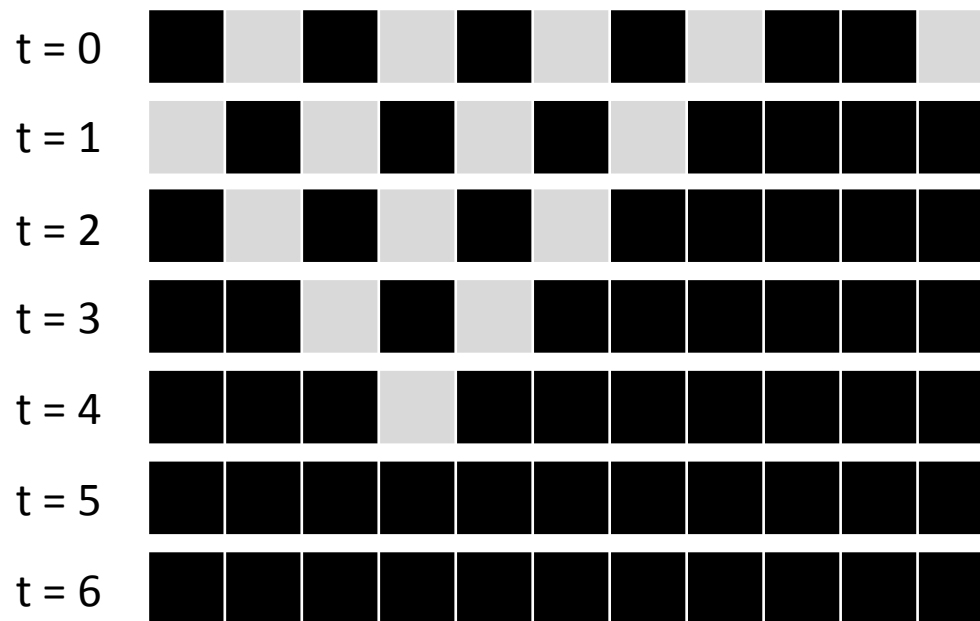


2. Majority Problem

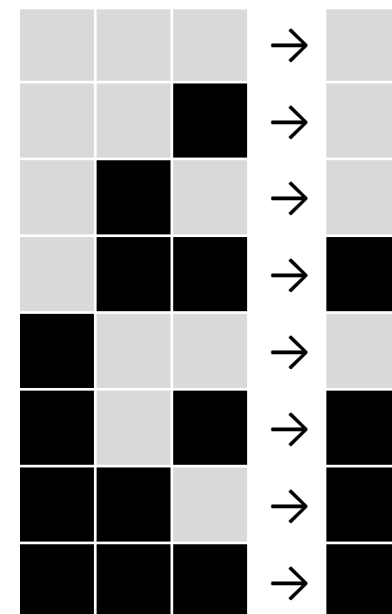
2. Majority Problem

Example 1: **solved**

Configuration



Rule



2. Majority Problem

Example 2: **unsolved**

Configuration

t = 0											
t = 1											
t = 2											
t = 3											
t = 4											
t = 5											
t = 6											

Rule

			→	
			→	
			→	
			→	
			→	
			→	
			→	
			→	

2. Majority Problem

Some important solutions for $r = 3$ and $n = 149$:

Year	Authors	Method	Performance
1978	Gács, Kurdyumov, Levin	human-written	81.6%
1994	Das, Mitchell, Crutchfield	Genetic Algorithm	76.9%
1995	Davis	human-written	81.8%
1995	Das	human-written	82.178%
1996	Andre, Bennett, Koza	Genetic Programming	82.326%
1998	Juillé, Pollack	Coevolutionary Learning	86.3%

2. Majority Problem

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Question: Does a perfect rule exist?

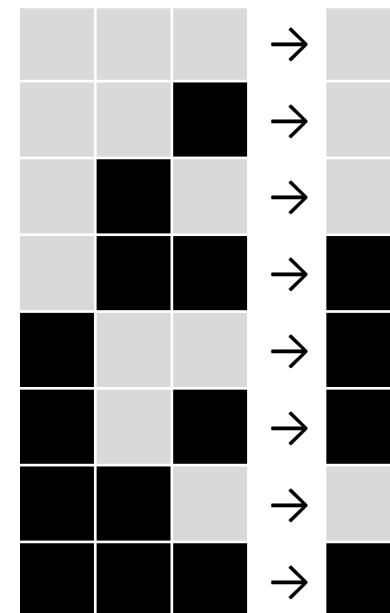
2. Majority Problem

Variation 1: (Capcarre, Sipper and Tomassini - 1996)

Change the output specification:

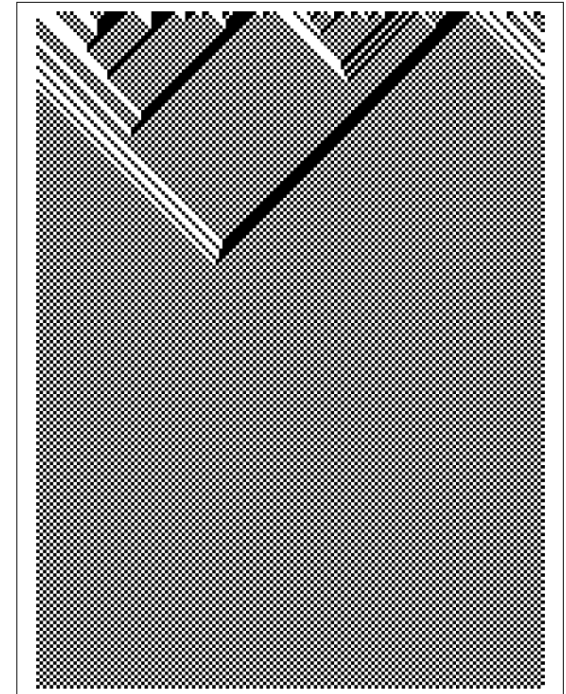
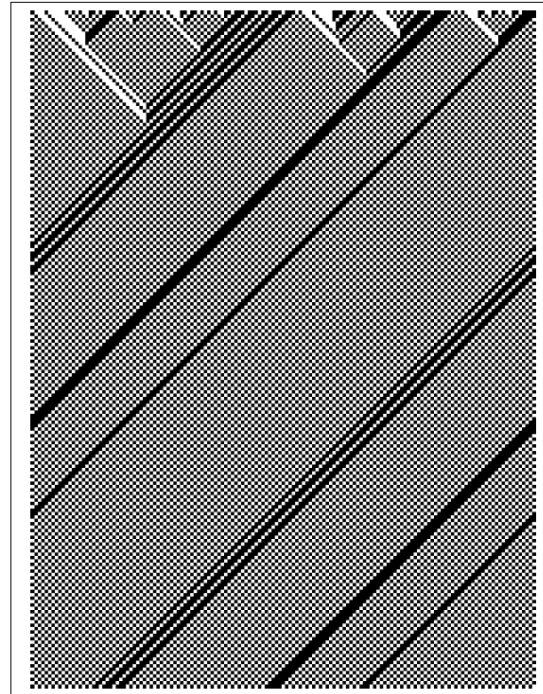
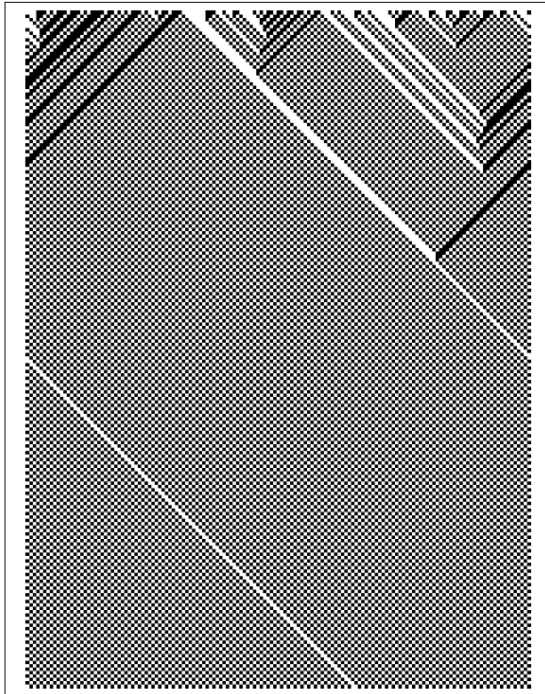
If the initial configuration contains more 1's (or 0's) than 0's (or 1's), no two cells with state 0 (or 1) can coexist in the final configuration.

Rule 184



2. Majority Problem

Variation 1: (Capcarre, Sipper and Tomassini - 1996)



Source: Mathieu S. Capcarrere, Moshe Sipper, and Marco Tomassini. Two-state, $r = 1$ Cellular Automaton that classifies density. *Physical Review Letter*, 77 (24):4969-4971, 1996.

2. Majority Problem

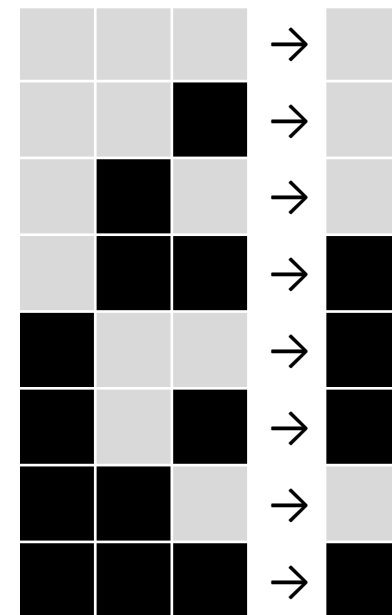
Variation 2: (Fuks - 1997)

Use two Cellular Automata:

Combine the use of Rule 184 and Rule 232.

First apply only Rule 184, then only Rule 232.

Rule 184



2. Majority Problem

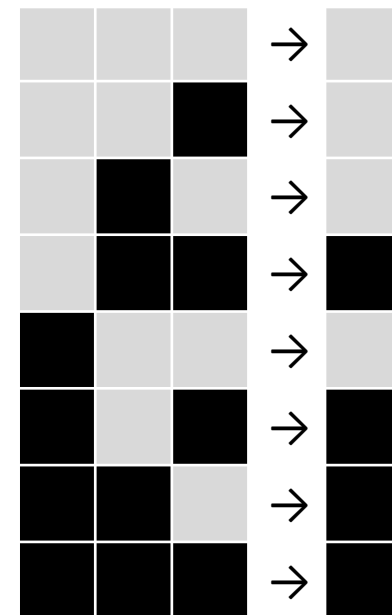
Variation 2: (Fuks - 1997)

Use two Cellular Automata:

Combine the use of Rule 184 and Rule 232.

First apply only Rule 184, then only Rule 232.

Rule 232

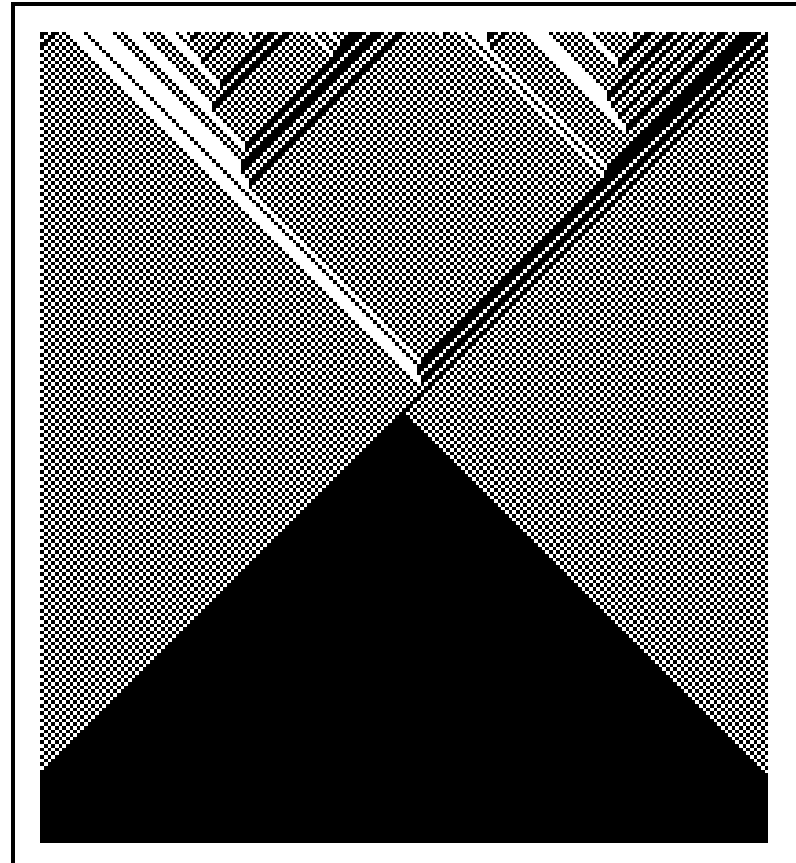


2. Majority Problem

Variation 2: (Fuks - 1997)

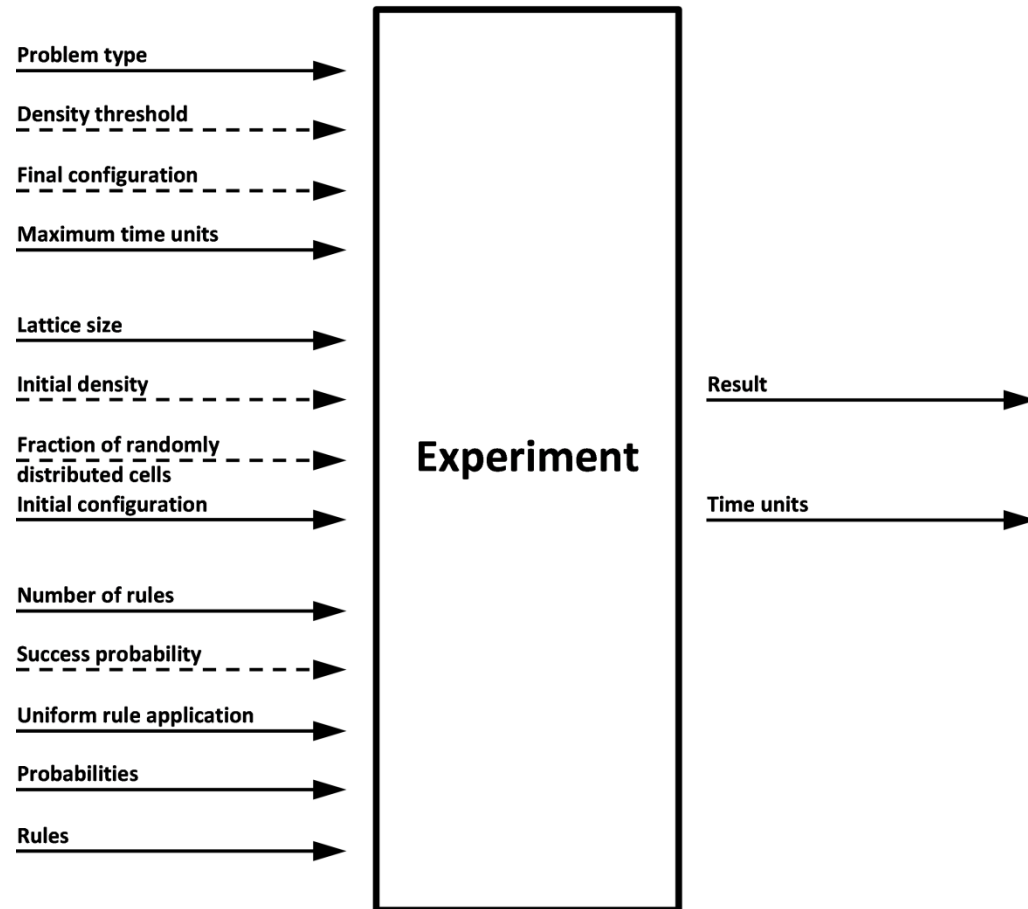
Rule 184

Rule 232

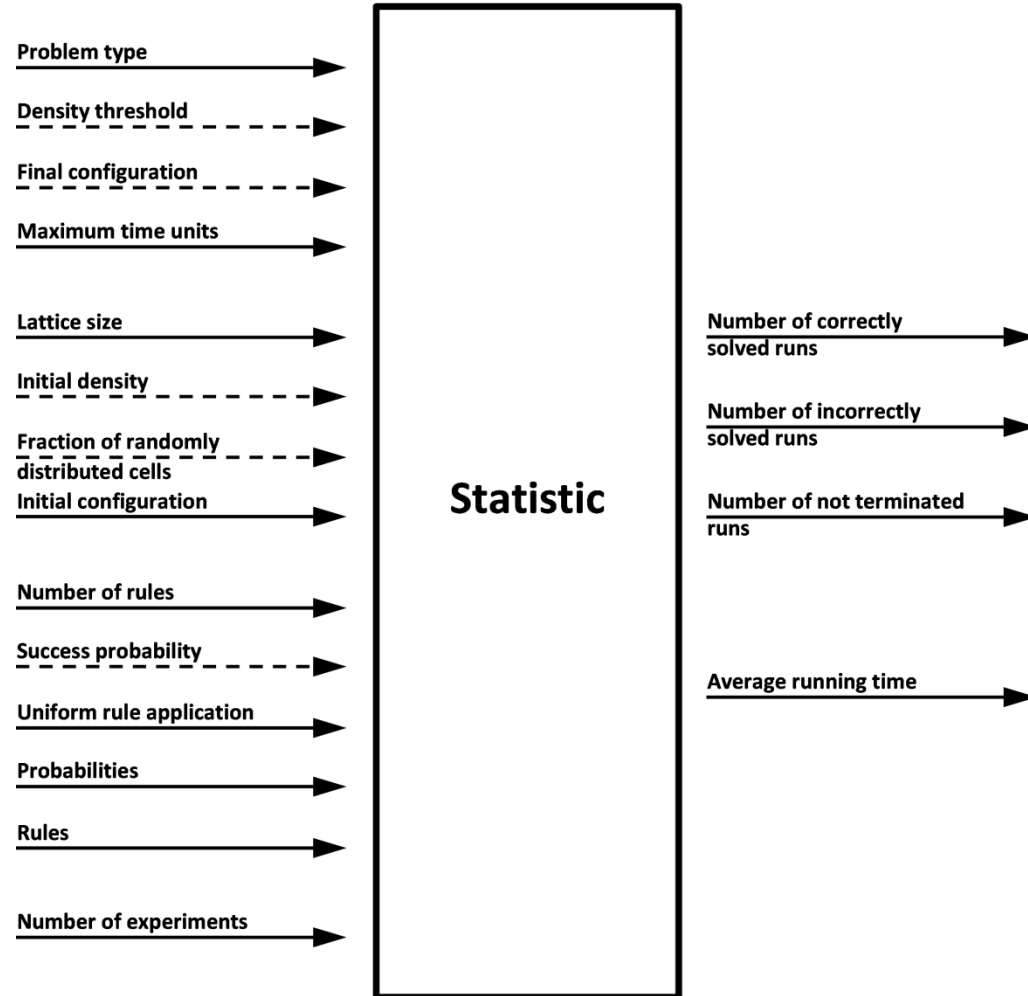


3. Tool

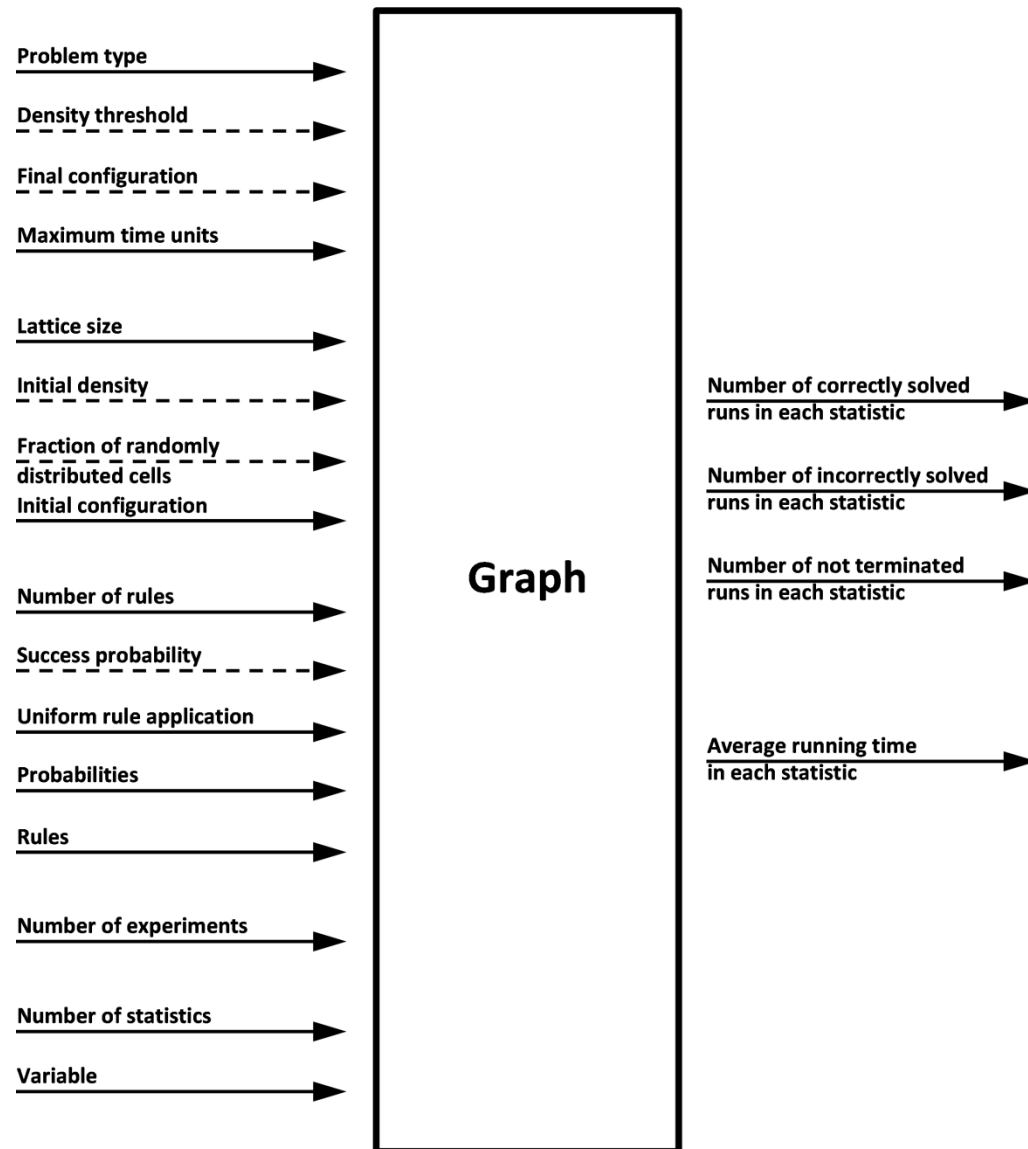
3. Tool



3. Tool

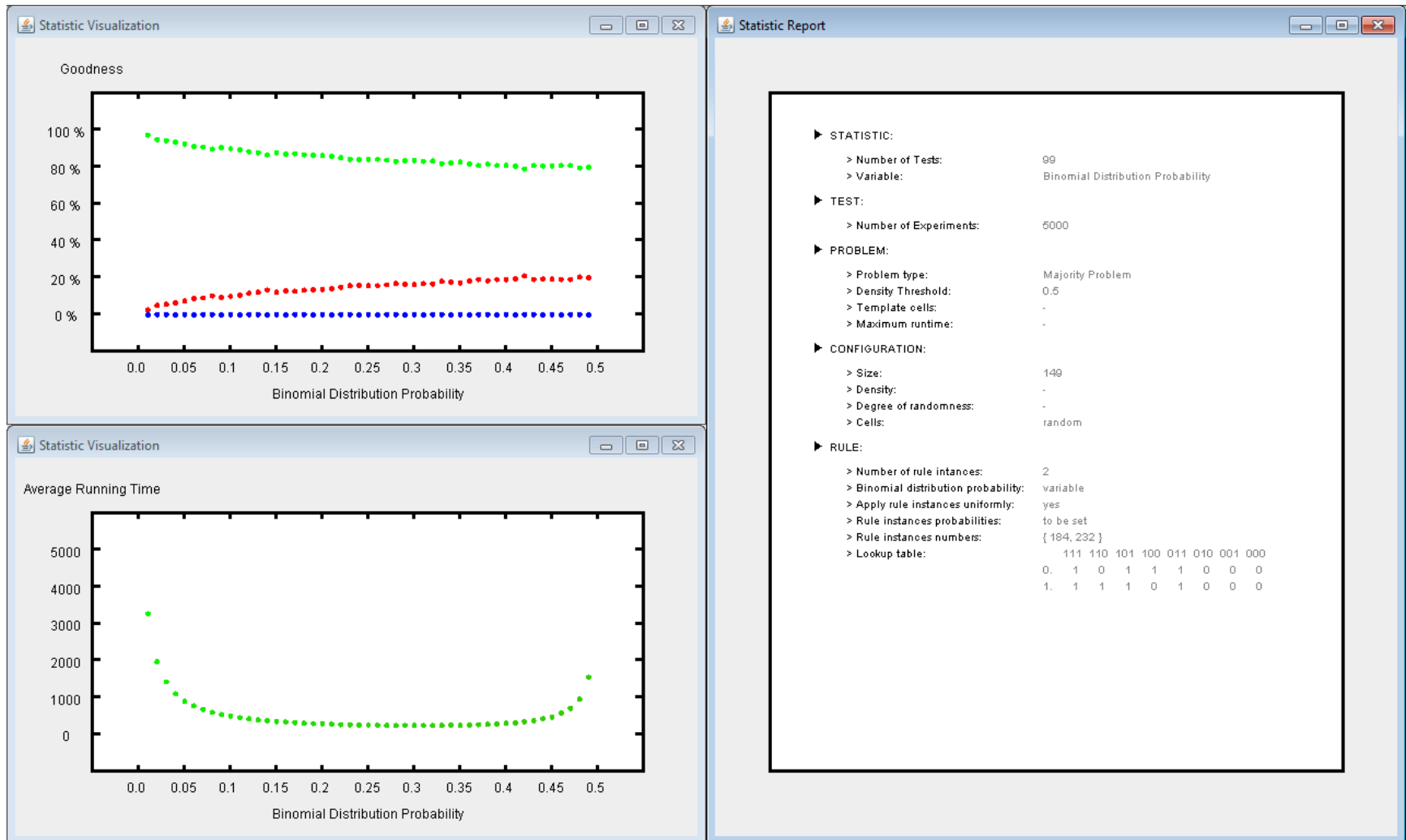


3. Tool



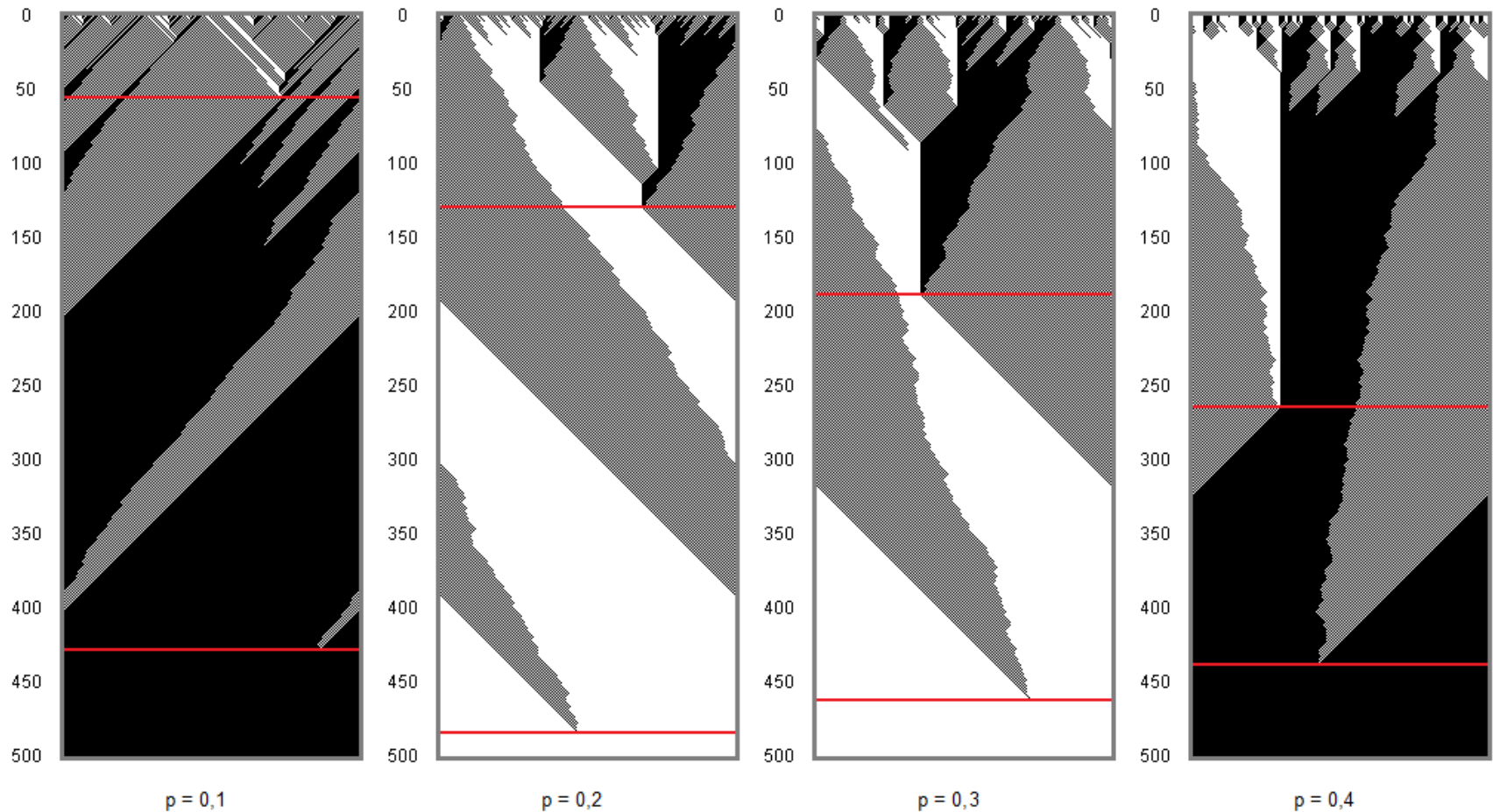
4. Analysis

4. Analysis



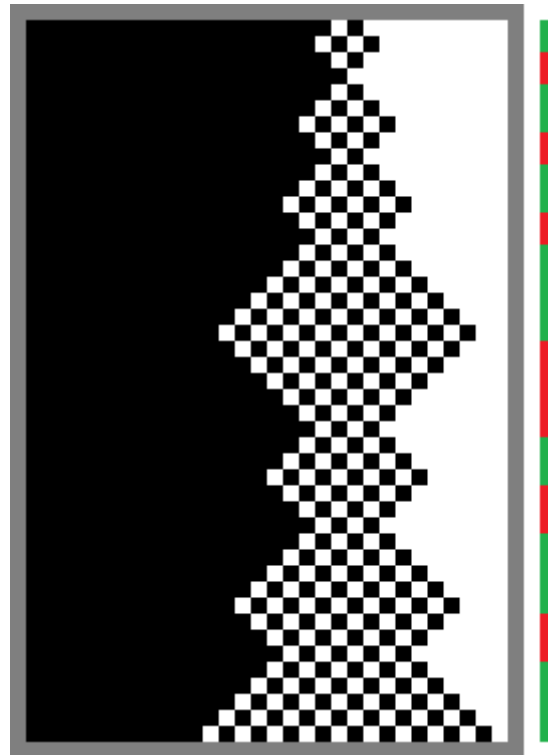
4. Analysis

Total running time as the sum of the running time of two phases:



4. Analysis

Phase 1 simulated with $n = 30$, $d = 2/3$ and $p = 0.4$:

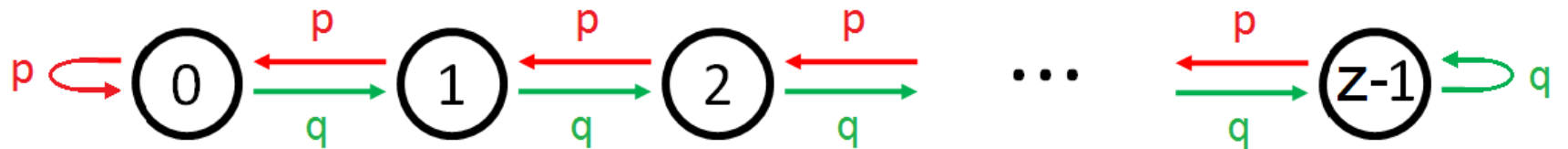


Green: Rule 184

Red: Rule 232

4. Analysis

Phase 1 modelled as a **random-walker**



$$(q = 1-p)$$

with **stochastic matrix** :

$$P = \begin{pmatrix} p & q & 0 & 0 & 0 & \dots & 0 & 0 \\ p & 0 & q & 0 & 0 & \dots & 0 & 0 \\ 0 & p & 0 & q & 0 & \dots & 0 & 0 \\ 0 & 0 & p & 0 & q & \dots & 0 & 0 \\ p & q & 0 & p & 0 & \ddots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \ddots & \ddots & q & 0 \\ 0 & 0 & 0 & 0 & \dots & p & 0 & q \\ 0 & 0 & 0 & 0 & \dots & 0 & p & q \end{pmatrix}$$

4. Analysis

Expected number of steps from state 0 to state $z-1$ for some z :

$$h_{0,z-1} = \begin{cases} 0, & \text{if } z = 1, \\ 1q^{-1}, & \text{if } z = 2, \\ 1q^{-1} + 1q^{-2}, & \text{if } z = 3, \\ 2q^{-1} + 0q^{-2} + 1q^{-3}, & \text{if } z = 4, \\ 2q^{-1} + 2q^{-2} - 1q^{-3} + 1q^{-4}, & \text{if } z = 5, \\ 3q^{-1} + 0q^{-2} + 3q^{-3} - 2q^{-4} + 1q^{-5}, & \text{if } z = 6, \\ 3q^{-1} + 3q^{-2} - 3q^{-3} + 5q^{-4} - 3q^{-5} + 1q^{-6}, & \text{if } z = 7, \\ 4q^{-1} + 0q^{-2} + 6q^{-3} - 8q^{-4} + 8q^{-5} - 4q^{-6} + 1q^{-7}, & \text{if } z = 8, \\ \vdots & \end{cases}$$

4. Analysis

Expected number of steps from state 0 to state $z-1$ for some z :

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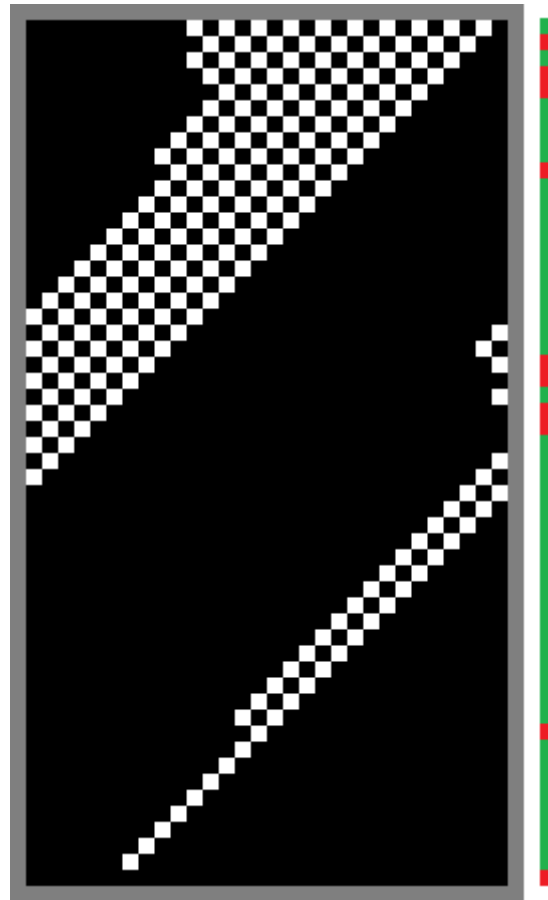
And as a recursion :

$$h_{0,0} = 0,$$

$$h_{0,z} = (h_{0,z-1} + z)q^{-1} - h_{0,z-1}$$

4. Analysis

Phase 2 simulated with $n = 30$, $d = 2/3$ and $p = 0.3$:

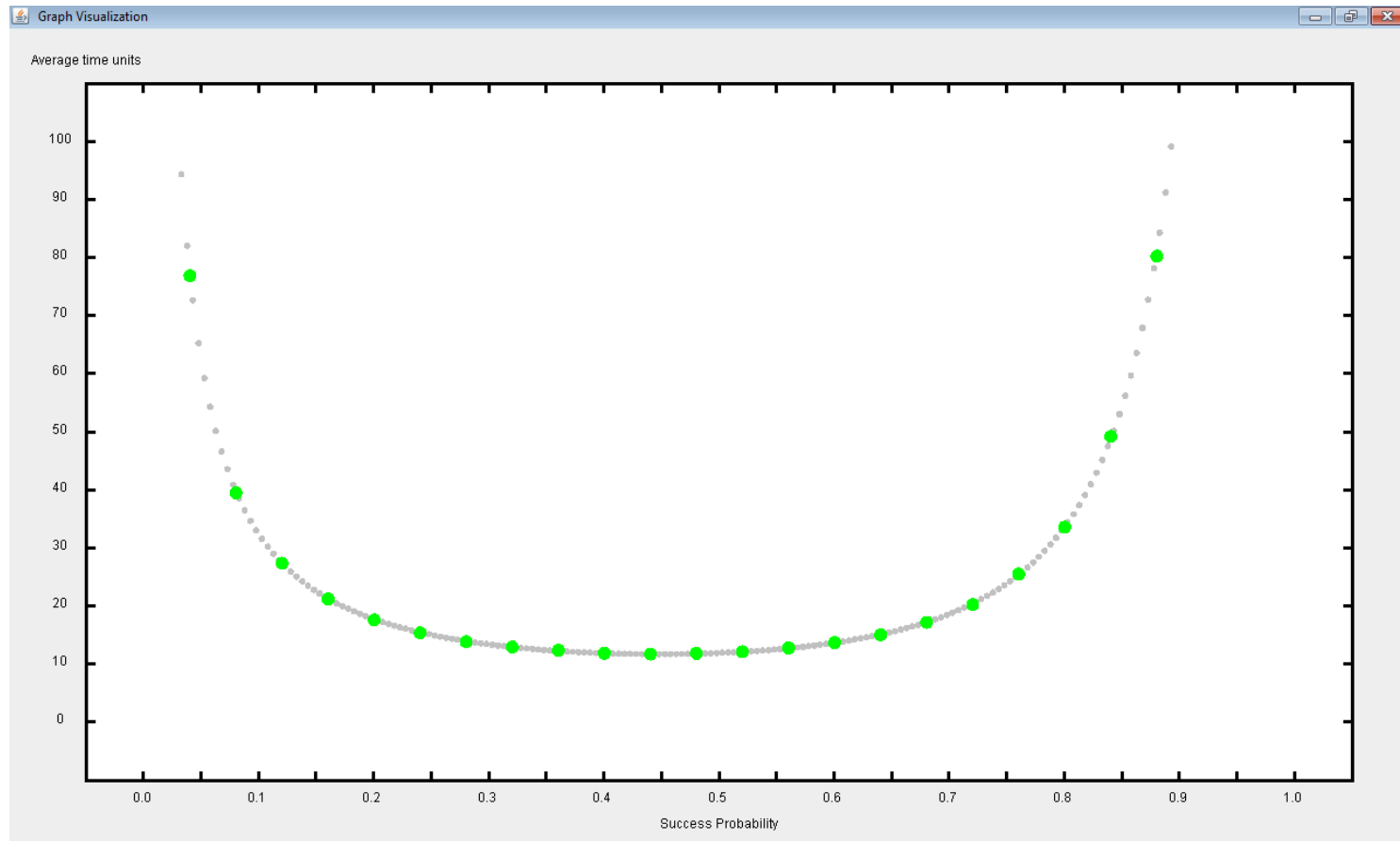


Green: Rule 184

Red: Rule 232

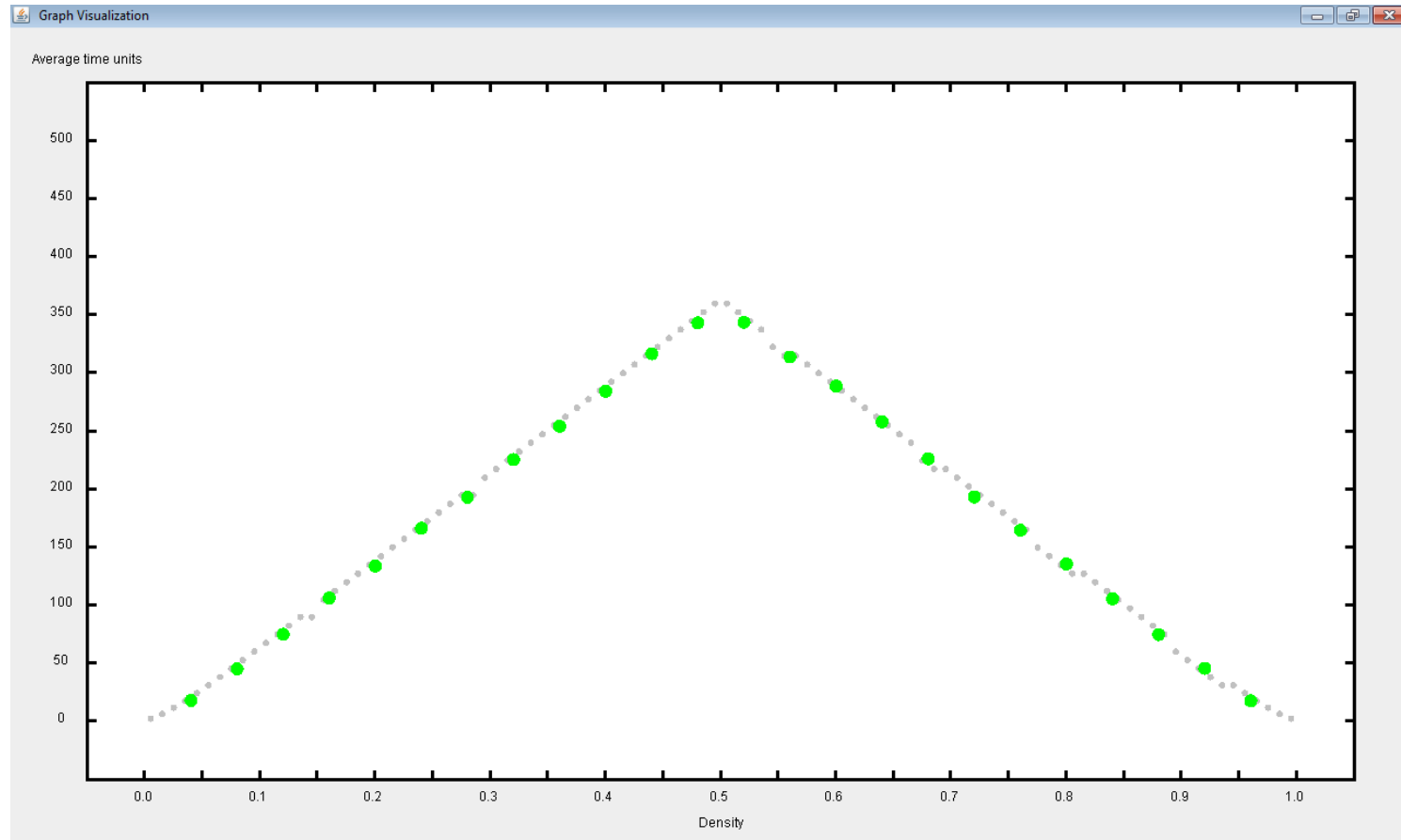
5. Results

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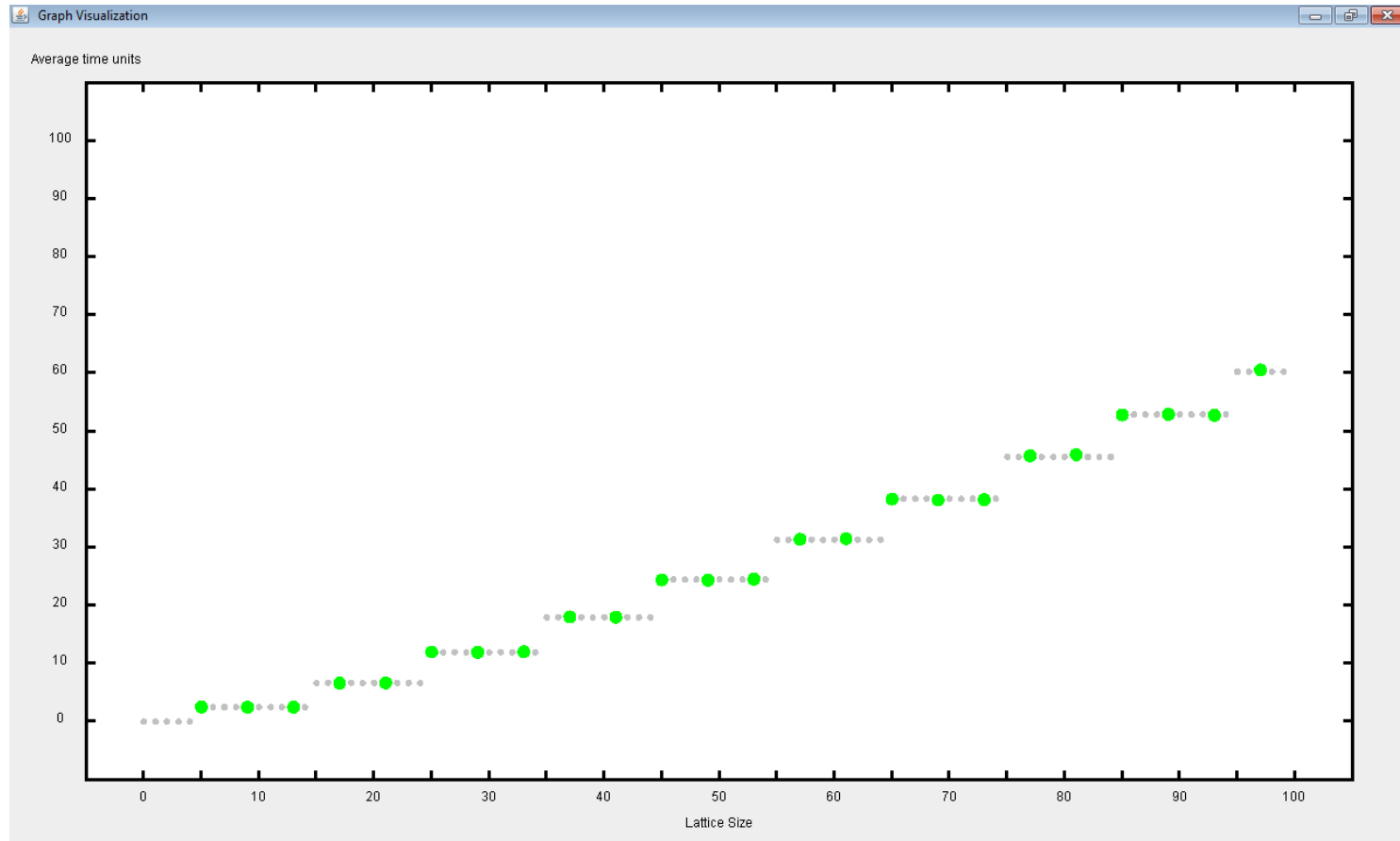
Running Time against p with $d = 0.3$ and $n = 10$

5. Results



Running Time against d with $p = 0.4$ and $n = 100$

5. Results



Running Time against n with $d = 0.1$ and $p = 0.4$

6. Conclusions

Expected time

$$\begin{aligned}\mathbb{E}[T] &= \mathbb{E}[T_1 + T_2] \\ &= \end{aligned}$$

Expected time

$$\begin{aligned}\mathbb{E}[T] &= \mathbb{E}[T_1 + T_2] \\ &= \mathbb{E}[T_1] + \mathbb{E}[T_2] \\ &= \end{aligned}$$

Expected time

$$\begin{aligned}\mathbb{E}[T] &= \mathbb{E}[T_1 + T_2] \\ &= \mathbb{E}[T_1] + \mathbb{E}[T_2] \\ &= \frac{p((\frac{p}{1-p})^{z-1} - z - 2) + (1-p)(z-1)}{(1-2p)^2} +\end{aligned}$$

Expected time

$$\begin{aligned}\mathbb{E}[T] &= \mathbb{E}[T_1 + T_2] \\ &= \mathbb{E}[T_1] + \mathbb{E}[T_2] \\ &= \frac{p\left(\left(\frac{p}{1-p}\right)^{z-1} - z - 2\right) + (1-p)(z-1)}{(1-2p)^2} + \frac{z}{p}\end{aligned}$$

Expected time

$$\begin{aligned}\mathbb{E}[T] &= \mathbb{E}[T_1 + T_2] \\ &= \mathbb{E}[T_1] + \mathbb{E}[T_2] \\ &= \frac{p\left(\left(\frac{p}{1-p}\right)^{z-1} - z - 2\right) + (1-p)(z-1)}{(1-2p)^2} + \frac{z}{p}\end{aligned}$$